# 2

### Start-up, control with I/O and ID run

#### Contents of this chapter

The chapter describes how to:

- · perform the start-up
- start, stop, change the direction of the motor rotation and adjust the speed of the motor through the I/O interface
- perform an Identification run (ID run) for the drive.

#### How to start up the drive

**Note:** Automatic selection of supply voltage is not supported in ACH580-31. You must select the supply voltage manually using parameter *95.01 Supply voltage*. Follow the instructions below.

#### How to start up the drive using the First start assistant on the Hand-Off-Auto control panel

	Safety								
	Do not start-up the drive unless you are a qualified electrician.								
L'	Kead and obey the instructions in chapter Safety instructions at the beginning of the								
Ha	rdware manual of the drive. Ignoring the instructions can cause physical injury or death, or								
dar	nage to the equipment								
	Check the installation. See chapter <i>Installation checklist</i> in the <i>Hardware manual</i> of the drive.								
	Make sure there is no active start on (DI1 in factory settings, that is, HVAC default). The drive will start up automatically at power-up if the external run command is on and the drive is in the external control mode.								
	Check that the starting of the motor does not cause any danger.								
	De-couple the driven machine if								
	<ul> <li>there is a risk of damage in case of an incorrect direction of rotation, or</li> </ul>								
	<ul> <li>a Normal ID run is required during the drive start-up, when the load torque is higher than 20% or the machinery is not able to withstand the nominal torque transient during the ID run.</li> </ul>								
	Hints on using the assistant control panel								
	The two commands at the bottom of the display (Options and Menu in the figure on the right), show the functions of the two softkeys and located below the display. The commands assigned to the softkeys vary depending on the context. Use keys (), (), () and () to move the cursor and/or change values depending on the active view. Key (?) shows a context-sensitive help page. For more information, see ACX-AP-x assistant control panels user's manual (3AUA0000085685 [English]).								
	1 – First start assistant guided settings:								
	Language, motor nominal values, and date and time								
	Have the motor name plate data at hand.								
	Power up the drive.								

	1
The First start assistant guides you through the first start-up. The assistant begins automatically. Wait until the control panel enters the view shown on the right. Select the language you want to use by	English Deutsch Suomi Français Italiano
highlighting it (if not already highlighted) and pressing (OK).	Nederlands Svenska
<b>Note:</b> After you have selected the language, it takes a few minutes to download the language file to the control panel.	ок <b>•</b>
<ul> <li><u>ACH580-31 drive</u>: Select the supply voltage with parameter 95.01 Supply voltage:</li> <li>In the First start assistant menu, select Exit and press (Next).</li> </ul>	
• In the Home view, press (Menu) to enter the Main menu.	
<ul> <li>In the Main menu, go to Parameters &gt; Complete list &gt; 95 HW configuration by selecting the correct row and pressing (Select) repeatedly.</li> </ul>	
• Select parameter <i>95.01 Supply voltage</i> and press (Edit).	
<ul> <li>Select supply voltage 380415 V or 440480 V and press (Save).</li> </ul>	
• Go back to the Main menu by pressing (Back) repeatedly.	
• In the Main menu, select <b>First start assistant</b> and press ( <b>Select</b> ) to enter the First start assistant menu.	
Continue with the following steps for commissioning the ACH580.	
Select Commission the drive and press (Next).	Off
	Set-up drive now?
	Spin the motor mode
	Exit & don't show at power-up Exit
	15:16 <b>Next</b>

Select the localization you want to use and press (Next).	Off C ACH580 Localization Unit defaults: International (SI) US standard (Imperial)	0.0 Hz
	Back 15:16	Next
Change the units shown on the panel if needed.	Off 🔷 🌈 ACH580	0.0 Hz
<ul> <li>Go to the edit view of a selected row by</li> </ul>	Units	
<ul> <li>Scroll the view with A and .</li> </ul>	Change the display units if n	ieeded.
Go to the next view by pressing 💭 (Next).	Temperature:	°C►
	Torque:	Nm►
	Currency:	€►
 <b>—</b> • • • • • • • • • • • • • • • • • • •	Back 15:17	Next
<ul> <li>Use ▲ and ♥ to select the value.</li> <li>Press ◯ (Save) to accept the new setting, or press ◯ (Cancel) to go back to the previous view without making changes.</li> </ul>	Off ACH580 Power: KW hp	0.0 Hz
	<b>Cancel</b> 15:17	Save
Set the date and time as well as date and time	Off 🔷 🌈 ACH580	0.0 Hz
<ul> <li>Go to the edit view of a selected row by pressing ▶.</li> <li>Scroll the view with ▲ and ▼.</li> <li>Go to the next view by pressing ◯ (Next).</li> </ul>	Date & time Please enter the current datu Date 2 Time Show date as day.m Show time as	■ and time. 4.02.2017 ► 15:17:50 ► onth.year ► 24-hour ►
	Back 15:17	Next

Refer to the motor nameplate for the following nominal value settings of the motor. Enter the values <u>exactly</u> as shown on the motor nameplate.

Example	e of a	nam	neplate	e of ar	n indu	ction	(asyr	nchror	nous) moto	r:	
( <del>-</del>		AE	BB M	otor	s	CE	-\$				
3 ~ moto	or	M2A	A 200 M	LA 4							
		IEC	200 M/L	55			~				
			N	0							
				ns.cl.	F	IP 5	5				
V	Hz	kW	r/min	A	cos g	PIA/IN	۲E/s				
690 Y	50	30	1475	32.5	0.83						
400 D 660 Y	50	30	1475	34	0.83						
380 D	50	30	1470	59	0.83						
415 D	50	30	1475	54	0.83						
440 D	60	35	1770	59	0.83						
Cat. no	3G	AA 202	2 001 - A	DA							
6212	100			10/02		100	l				
6312/	103	-	62	10/03		180	Kg				
⊕					IEC 34	4-1	Ð				
Check the	hat th	ne mo	otor da	ta is o	correc	ct. Va	lues a	are	0ff <b>◊</b>	C ACH580	0.0 Hz
should v	ea o /erifv	n the that	basis thev c	orthe	ond :	e size	e but y e moto	/ou or	Motor no	minal values	
Start wit	h the	emot	or type	).					Find the v	alues on the mot	tor's
Go to	the e	edit v	iew of	a sele	ected	row I	bv		namepiate Custopti	e, and enter then	n nere: 1 2 A <b>s</b> N
press	ing (	▶.					.,		Speed:		1360 rom ►
<ul> <li>Scroll</li> </ul>	the	view	with 📥	and					Voltage:		230.0 V ►
Motor no	omina	al cos	sΦan	d non	ninal	torqu	e are		Back	15.18	Next
optional									Dack	10.10	NCAL
Press <	$ \ge $	(Nex	t) to co	ontinu	e.						
To chan	ge a	value	e in an	edit v	view:				Off <b></b>	🌈 ACH580	0.0 Hz
• Use L	∎) ar	nd 🕩	] to mo	ove th	e cur	sor le	eft and	d	Current:		
• Lise [	▲] ar	nd 🗲	to ch	ange	the v	alue				1 6	
Press 🤆		(Save	e) to a	ccent	the n	ew se	ettina	or		Ⅰ.⊿ ∧	
press [-	$\overline{\supset}$	Can	cel) to	ao ba	ack to	the r	orevic	ous		_	
view wit	hout	maki	ng cha	inges					<u> </u>	•	4.0
			0	Ũ					0.0		4.0
									Cancel	15:18	Save
This ste	p is c	ptior	al, an	d requ	lires	rotatiı	ng the	e	0ff�	<b>(*</b> ACH580	0.0 Hz
the mec	hanio	t do t cal se	nis it it et-un d	could oes n	ot all	se any ow it	y risk,	, or it	Direction	i test?	
To do th	o dire		n tost		t Snir	a tha	moto		Spin the n	notor to check d	irection?
and pres			Next)	30100	t opii	i uie	mote	,	Spin the r	motor	
	50 \		itext).						Not now		
										15.10	
									Back	15:19	Next

Press the Hand key $\bigotimes_{Hand}$ on the panel to start the	Off� (~ ACH580 5.0 Hz
Check the direction of the motor.	Uff ◆       ( ▲ ACH580       5.0 Hz         Press Hand       ■         Warning: Until set-up is done, safeties are not active and motor speed is 5 Hz.         Press Hand now to spin the motor, then check the direction of rotation.         Back       15:19         Hand ◆       ▲ ACH580       \$5.0 Hz         Is this forward?       ■
If the direction is not forward, select <b>No</b> , <b>fix</b> <b>direction</b> and press (Next) to continue.	Selecting "No, fix direction" tells the drive to change direction, and labels the new direction "forward". Yes, motor is spinning forward No, fix direction 15:19 <b>Next</b>
The first start is now complete and the drive is ready for use. Press (Done) to enter the Home view.	Off ◆
The Home view 1 monitoring the values of the selected signals is shown on the panel. There are eight different Home view displays. Home view 1 is the default Home view. You can browse them with keys ( ) and ( ). See section <i>Home view displays</i> on page <i>47</i> .	Off ACH580 0.0 Hz Output frequency Hz 0.00 Motor current All actual value V 0.000 Options 15:19 Menu





	3 – Additional settings in the Primary settings menu – I/O menu						
	After the additional adjustments, make sure that	0ff�	<b>(*</b> ACH580	0.0 Hz			
	control program.	Main me	nu ———	0			
	In the Main menu, select a I/O and press 🤙	Pr Pr	imary settings	•			
	(Select) to enter the I/O menu.		0	► 1			
		Di Di	agnostics	•			
		Exit	15:20	Select			
	Select a the connection you want to check and	0ff <b></b>	<b>(~</b> ACH580	0.0 Hz			
	press (Select) (or ).	I/0 —					
		DI1: 0		Start/stop 🕨			
		DI2: 0	llead in sav	Not used •    • ral places •			
		DI4: 1	Osed in sevi	Not used ►			
		DI5: 0		Not used 🕨			
		Back	15:20	Select			
	To view the details of a parameter that cannot be	0ff <b></b>	<b>(~</b> ACH580	0.0 Hz			
	adjusted via the <b>I/O</b> menu, press (View).	DI1: —					
		Actual va	alue:	0			
		L Force	input state	04			
		Off delay	r.	0.0 s			
		On delay		0.0 s			
		Back	15:21	View			
	To adjust the value of a parameter, press	Off�	<b>(~</b> ACH580	0.0 Hz			
_	(Edit), adjust the value using $\land$ , $\checkmark$ , $\checkmark$ and $\triangleright$	DI1: —					
	wiring must match the new value.	🗆 Force	input state	4			
	Go back to the <b>Main</b> menu by pressing 🥏	Input sta	102 1	Off			
	(Back) repeatedly.	Off delay	r.	0.0 s			
		Used for		0.0 s Start/stop			
		Back	15:21	Edit			
		0ff <b></b>	ACH580	0.0 Hz			
		Used fo	г:				
		Not us	ed	Q			
		DI1 sta	irt/stop				
		DI1 sta	ward DI2 revers	e			
		DI1P st	tart, DI2 stop	-			
		Cancel	15:21	Save			

4 – Diagnostics n	menu	
After making the additional adjustments and	Off� <b>(*</b> ACH580 0	.0 Hz
<b>Diagnostics</b> menu to make sure that the setup is functioning correctly.	Main menu — Primary settings	•
In the Main menu, select Diagnostics and press (Select) (or ().	1/0	•
	A Diagnostics	•
	Exit 15:22 So	elect
Select the diagnostics item you want to view and	0ff� <b>(*</b> ACH580 0	1.0 Hz
Press (Select).	Diagnostics ————	
(Back).	Drive actual values	►
	Active warmings	
	Active inhibits	ľ
	Fault & event log	•
	Back 15:22 Se	elect

#### How to control the drive through the I/O interface

The table below describes how to operate the drive through the digital and analog inputs when:

- · the motor start-up is performed, and
- the default parameter settings of the HVAC default configurations are in use.

Preliminary settings						
If you need to change the direction of rotation, check that limits allow reverse direction. Check parameter group <i>30 Limits</i> and make sure that the minimum limit has a negative value and the maximum limit has a positive value.						
Note: Default settings only allow forward direction.						
Make sure that the control connections are wired according to the connection diagram given for the HVAC default.	See section <i>HVAC default</i> on page <i>83</i> .					
Make sure that the drive is in external control. To switch to external control, press key Auto.	In external control, the panel display shows text <b>Auto</b> at the top left.					
Starting and controlling the sp	eed of the motor					
Start by switching digital input DI1 on. The arrow starts rotating. It is dotted until the setpoint is reached. Regulate the drive output frequency (motor speed) by adjusting voltage of analog input AI. <b>Note:</b> If the drive will not start, check that the start interlock 1 (parameter <i>20.41</i> ) is active (1). For the HVAC default, the start interlock 1 is connected to DI4 by default.	Auto ACH580 0.7 Hz Output frequency Hz 0.00 Motor current A 0.47 All actual value V 4.260 Options 12:30 Menu					
Stopping the mo	tor					
Switch digital input DI1 off. The arrow stops rotating.	Auto C ACH580 0.7 Hz Output frequency 0.00 Hz 0.00 ▲ Motor current 0.00 Al1 actual value 4.260 Options 12:31 Menu					

#### How to perform the ID run

The drive automatically estimates motor characteristics using *Standstill* ID run when the drive is started for the first time in vector control and after any motor parameter (group *99 Motor data*) is changed. This is valid when

- parameter 99.13 ID run requested selection is Standstill and
- parameter 99.04 Motor control mode selection is Vector.

In most applications there is no need to perform a separate ID run. The ID run should be selected manually if:

- vector control mode is used (parameter 99.04 Motor control mode is set to Vector), and
- permanent magnet motor (PM) is used (parameter 99.03 Motor type is set to Permanent magnet motor), or
- synchronous reluctance motor (SynRM) is used (parameter 99.03 Motor type is set to SynRM), or
- · drive operates near zero speed references, or
- operation at torque range above the motor nominal torque, over a wide speed range is needed.

Do the ID run with the ID run assistant by selecting **Menu > Primary settings > Motor > ID run** (see page 35) or with parameter 99.13 ID run requested (see page 39).

Note: If motor parameters (99 Motor data) are changed after the ID run, it must be repeated.

**Note:** If you have already parameterized your application using the scalar motor control mode (99.04 *Motor control mode* is set to *Scalar*) and you need to change motor control mode to *Vector*,

change the control mode to vector with the Control mode assistant (go to Menu
 Primary settings > Motor > Control mode) and follow the instructions. The ID
 run assistant then guides you through the ID run.

or

- set parameter 99.04 Motor control mode to Vector, and
  - for I/O controlled drive, check parameters in groups 22 Speed reference selection, 23 Speed reference ramp, 12 Standard AI, 30 Limits and 46 Monitoring/scaling settings.

#### ID run procedure

#### With the ID run assistant

	Pre-check									
<u> </u>	WARNING! The motor will run at up to approximately 5080% of the nominal speed during the ID run. The motor will rotate in the forward direction. Make sure that it is safe to run the motor before performing the ID run!									
	De-couple the motor from the driven equipment									
	Check that the values of the motor data parameters are equivalent to those on the motor nameplate.									
	Check that the STO circuit is closed.									
	The assistant will ask if you want to use tempora following conditions:	ry motor limits. They must meet the								
	Minimum speed $\leq$ 0 rpm									
	Maximum speed = motor rated speed (Normal ID run procedure needs the motor to be run at 100% speed.)									
	Maximum current > I <sub>HD</sub>									
	Maximum torque > 50%									
	Make sure that the panel is in the Off mode control (text Off shown at the top left). Press the Off key $$ to switch to the Off mode.									
	ID run									
	Go to the <b>Main</b> menu by pressing (Menu)	Off� <b>(</b> ▲ ACH580 0.0 Hz								
	Select <b>Primary settings</b> and press	Main menu ———								
	(Select) (or ▶).	Primary settings								
		I/0 ►								
		🖅 Diagnostics 🔹 🕨								
		Exit 22:47 Select								
	Select Motor and press (Select) (or ).	Auto C ACH580 0.0 Hz								
		Primary settings								
		HVAC quick setup								
		Motor								
		Ramps 🕨								
		Limits								
		Back 22:47 Select								

continue to the next step.	If the control modes is scalar, select <b>Control</b> mode and press (Select) (or ()) and	Auto C ACH580 0.0 Hz
✓Concol mode       Set         Select Vector control and press       (Select)         Off ◇ C* ACH580       0.1         Naming message Identification run is shown.       Press         Press       (Hide) to continue.         Warning message Identification run is shown.       Off ◇ C* ACH580       0.0         Press       (Hide) to continue.       Off ◇ C* ACH580       0.0         Maximum speed ≤ 0 rpm       Maximum speed = motor rated speed.       Auto C* ACH580       0.0         Iminum speed ≤ 0 rpm       Maximum speed       1500.00 rp       Maximum current       2.92         Back       22.49       N       N       The following must be true:       Auto C* ACH580       0.0         • Maximum current > / <sub>HD</sub> Maximum current       2.92       N       N       These motor limits       These motor limits         • Maximum current > / <sub>HD</sub> • Maximum current > / <sub>HD</sub> These motor limits apply to vector control and uses if needed:       Max	continue to the next step.	XNominal values
Back       22:48       Sel         Back       22:48       Sel         Off ◇ (* ACH580)       0.0         (or ●).       Off ◇ (* ACH580)       0.0         Control mode       Some settings depend on the control mode. If you change the mode, the system will help you to adjust these Scalar control         Vector control       Back       22:48       Sel         Warning message Identification run is shown.       Press       Off ◇ (* ACH580)       0.0         Press       (Hide) to continue.       Off ◇ (* ACH580)       0.0         Maximum speed       Identification run       22:48       Motor identification run       22:48         Motor identification run       Sel       Sel       Sel       Sel       Sel         D       Check the motor speed limits. The following must be true:       Maximum speed ≤ 0 rpm       Hide       22:48       Motor identification run about to be performed         Hide       22:48       How tor       Imits       These motor limits       These motor limits         Naximum speed = motor rated speed.       Maximum speed       1500.00 rpm       Maximum speed       1500.00 rpm         Maximum current > / <sub>HD</sub> Maximum speed       1500.00 rpm       Maximum speed       1500.00 rpm         Maximum speed       1500		Control mode Scalar Start mode: Flying start (Automatic) Phase order: UVW Switching frequency 4 kHz ►
Select Vector control and press       (Select)         (or ●).       Off◆ 个 ACH580 0.0         Control mode       Some settings depend on the control mode. If you change the mode, the system will help you to adjust these Scalar control         Vector control       Back 22:48 Sel         Off◆ 个 ACH580 0.0       Vector control         Press       (Hide) to continue.         Off◆ 个 ACH580 0.0       Off◆ 个 ACH580 0.0         Maximum speed ≤ 0 rpm       Warning messed ≤ 0 rpm         • Maximum speed = motor rated speed.       Auto 个 ACH580 0.0         Minimum speed ≤ 0 rpm       Auto 个 ACH580 0.0         • Maximum speed = motor rated speed.       Maximum speed 1500.00 rpm         Maximum current 2.92 / Back 22:49 N       Auto 个 ACH580 0.0         Maximum speed = motor rated speed.       Minimum speed 1500.00 rpm         Maximum current 2.92 / Back 22:49 N       Maximum speed 1500.00 rpm         Maximum current 2.92 / Back 22:49 N       Maximum speed 1500.00 rpm         Maximum current > / <sub>HD</sub> Maximum speed 1500.00 rpm         • Maximum current > / <sub>HD</sub> Maximum speed 1500.00 rpm         • Maximum current > / <sub>HD</sub> Maximum speed 1500.00 rpm         • Maximum current > 2.92 / Maximum current 2.92 / Maximum speed 1500.00 rpm		Back 22:48 Select
Check the motor speed limits. The following must be true:       Maximum speed ≤ 0 rpm         Maximum speed ≤ 0 rpm       Maximum speed 1500.00 rpm Maximum current 2.92 / Back 22:49 N         Check the motor current as well as torque limits. The following must be true:       Auto C ACH580 0.0         Maximum current > / <sub>HD</sub> Auto C ACH580 0.0         Maximum torque > 50%.       Press (Next).	(or ).	Off C ACH580 0.0 Hz
Warning message Identification run is shown.       Off ◆ C* ACH580 0.0         Press → (Hide) to continue.       Warning AFF6         Aux code: 0000 0000       Identification run 22:48         Motor identification run about to be performed       Hide 22:48         Hide       22:48         Motor identification run about to be performed         Check the motor speed limits. The following must be true:       Auto C* ACH580 0.0         Minimum speed ≤ 0 rpm       Auto C* ACH580 0.0         Maximum speed = motor rated speed.       These motor limits apply to vector The following must be true:         Check the motor current as well as torque limits. The following must be true:       Auto C* ACH580 0.0         Check the motor current as well as torque limits. The following must be true:       Auto C* ACH580 0.0         Maximum current > <i>I</i> <sub>HD</sub> Auto C* ACH580 0.0         Naximum torque > 50%.       These motor limits apply to vector control. Adjust the values if needed:         Maximum speed 1500.00 rpm Maximum current 2.92 / Minimum torque 1 500.00 rpm Maximum current 2.92 / Minimum current 2.92 / Minimum current 2.92 / Minimum torque 1 500.00 rpm		Some settings depend on the control mode. If you change the mode, the system will help you to adjust these. Scalar control Vector control Back 22:48 Select
Press → (Hide) to continue.	Warning message <b>Identification run</b> is shown.	0ff 🔷 🌈 ACH580 0.0 rpm
□       Check the motor speed limits. The following must be true:       • Minimum speed ≤ 0 rpm         • Maximum speed ≤ 0 rpm       • Maximum speed = motor rated speed.         • Maximum speed = motor rated speed.       Check motor limits apply to vector control. Adjust the values if needed:         • Minimum speed = motor rated speed.       Minimum speed 1500.00 rpr Maximum current 2.92 / Maximum speed 1500.00 rpr Maximum current 2.92 / Back 22:49 N         □       Check the motor current as well as torque limits. The following must be true:       Auto C* ACH580 0.0         • Maximum current > / <sub>HD</sub> • Maximum torque > 50%.       These motor limits apply to vector control. Adjust the values if needed:         • Maximum torque > 50%.       Press ◯ (Next).       Maximum speed 1500.00 rpr Maximum current 2.92 / Minimum torque 1 -300.09		Warning AFF6 Aux code: 0000 0000 Identification run 22:48:10 Motor identification run about to be performed
be true:       Minimum speed ≤ 0 rpm         Maximum speed = motor rated speed.       Check motor limits         Maximum speed = motor rated speed.       These motor limits apply to vector control. Adjust the values if needed:         Minimum speed       1500.00 rpm         Maximum current       2.92 /         Back       22:49         Maximum current > / <sub>HD</sub> Maximum torque > 50%.         Press ◯ (Next).       Next).	Check the motor speed limits. The following must	
<ul> <li>Minimum speed ≤ 0 rpm</li> <li>Maximum speed = motor rated speed.</li> <li>Maximum speed = motor rated speed.</li> <li>Minimum speed = 0.00 rpf Maximum speed 1500.00 rpf Maximum current 2.92 / Back 22:49 N</li> <li>Check the motor current as well as torque limits. The following must be true:</li> <li>Maximum current &gt; I<sub>HD</sub></li> <li>Maximum torque &gt; 50%. Press (Next).</li> <li>Mextinum speed 1500.00 rpf Maximum speed 1500.00 rpf Maximum speed 1500.00 rpf Maximum speed 1500.00 rpf Maximum current 2.92 / Maximum speed 1500.00 rpf Maximum speed 1500.00 rpf</li> </ul>	be true:	Check motor limits
Maximum speed       1500.00 rpr         Maximum current       2.92 /         Back       22:49         N       Back         Check the motor current as well as torque limits.       Auto         The following must be true:       Auto         Maximum current > / <sub>HD</sub> Maximum torque > 50%.         Press ◯ (Next).       These motor limits apply to vector control. Adjust the values if needed:         Maximum speed       1500.00 rpr         Maximum current       2.92 /         Maximum torque > 50%.       Maximum speed         Press ◯ (Next).       1500.00 rpr         Maximum current       2.92 /	<ul> <li>Minimum speed &lt; 0 rpm</li> <li>Maximum speed = motor rated speed.</li> </ul>	These motor limits apply to vector control. Adjust the values if needed: Minimum speed 0.00 rom >
Maximum current       2.92 /         Back       22:49         Naximum current       2.92 /         Maximum current > / <sub>HD</sub> ACH580       0.0         Maximum torque > 50%.       Maximum speed       These motor limits apply to vector control. Adjust the values if needed:         Maximum speed       1500.00 rpm         Maximum current       2.92 /         Minimum torque 1       -300.0 9		Maximum speed 1500.00 rpm ►
□       Check the motor current as well as torque limits. The following must be true:       • AcH580       0.0         • Maximum current > I <sub>HD</sub> • Maximum torque > 50%.       • Maximum speed       1500.00 rpm         • Press ◯ (Next).       • Maximum current       2.92 / Minimum torque 1       -300.0 9		Maximum current 2.92 A ► Back 22:49 Next
Back 22.40 M	<ul> <li>Check the motor current as well as torque limits. The following must be true:</li> <li>Maximum current &gt; I<sub>HD</sub></li> <li>Maximum torque &gt; 50%.</li> <li>Press (Next).</li> </ul>	Auto       C ACH580       0.0 rpm         Check motor limits       ■         These motor limits apply to vector control. Adjust the values if needed:       Maximum speed       1500.00 rpm         Maximum speed       1500.00 rpm       Maximum current       2.92 A         Minimum torque 1       -300.0 %       Not

Check Al1 scaling, see parameters 12.19 Al1	Off� 🌈 ACH580 0.0 rpm
scaled at AI1 min and 12.20 AI1 scaled at AI1	Check other functions
max. Press (Next).	Vector control uses rpm values instead of Hz. Adjust the values if needed: All scaled min: 0.000 rpm ► All scaled max: 1500.000 rpm ► Back 22:48 Next
Select the type of ID run you want to do and press (Next).	Off ACH580 0.0 rpm ID run? Select what kind of ID run to do, if any.Press [?] for more information. Standstill (default) Normal Reduced 
	Back 22:48 Next
Check the motor limits shown on the panel. If you need other limits during the ID run you can enter them here. The originals limits will be restored after the ID run, unless you select <b>Set values as permanent</b> . Press (Next).	Off ◆ C* ACH580 0.0 rpm Motor limits ■ If you need special limits during theID run, adjust the values now. Current values are restored after the ID run. Set values as permanent Select ► Minimum speed 1500.00 rpm ► Back 22:49 Next
Press the Hand key ( ) to start the ID run. In general, it is recommended not to press any control panel keys during the ID run. However, you can stop the ID run at any time by pressing the Off key ( ). During the ID run a progress view is shown. After the ID run is completed, text <b>ID run done</b> is shown. The LED stops blinking. If the ID run fails, fault <i>FF61 ID run</i> is shown. See chapter <i>Fault tracing</i> on page <i>183</i> for more information.	Off ◆
	22:50

After the ID run is completed, text <b>Done</b> is shown	0ff <b>� (</b>	ACH580	0.0 rpm
on row <b>ID run</b> .	Motor —		
	🔨 Nominal v	alues	
	🕂 Control m	ode	Vector
	👗 ID run		Done
	Start mode:	Flying start	(Automatic)
	Phase order:		UVW
	Back	22:51	Select

#### With parameter 99.13 ID run requested

Pre-check							
WARNING! The motor will run at up to approximately 5080% of the nominal speed during the ID run. The motor will rotate in the forward direction. Make sure that it is safe to run the motor before performing the ID run!							
	De-couple the motor from the driven equipment						
	Check that the values of the motor data parameters are equivalent to those on the motor nameplate.						
	Check that the STO circuit is closed.						
	If parameter values (from group <i>10 Standard DI, RO</i> to group <i>99 Motor data</i> ) are changed before the ID run, check that the new settings meet the following conditions:						
	<i>30.11 Minimum speed</i> ≤ 0 rpm						
	30.12 Maximum speed = motor rated speed (Normal ID run procedure needs the motor to be run at 100% speed.)						
	30.17 Maximum current > I <sub>HD</sub>						
	<i>30.20 Maximum torque 1</i> > 50% or <i>30.24 Maximum torque 2</i> > 50%, depending on which torque limit set is in use according to parameter <i>30.18 Torq lim sel</i> .						
	Check that signals						
	run permissive (parameter 20.40 Run permissive)	is active					
	Make sure that the panel is in the Off mode control (text Off shown at the top left). Press the Off key $\textcircled{0}$ to switch to the Off mode.						
ID run							
	Go to the <b>Main</b> menu by pressing (Menu)	Off 🔷 🌈 ACH580 0.0 rpm					
	Press	Main menu					
		Primary settings					
		IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII					
		Diagnostics					
		Exit 22:51 Select					
	Select Parameters and press (Select) (or	0ff� <b>(~</b> ACH580 0.0 rpm)					
	▶).	Main menu					
		Energy efficiency 🕨 🕨					
		🛞 Backups 🕨					
		Parameters					
		Exit 22:51 Select					

Select Complete list and press (Select)	0ff�	C ACH580	mar 0.0
(or (▶).	Parameters		
	Complete List		
	Favorites		•
	Modified		•
	Back	22.51	Salact
	Dack	22.01	JEIELL
Scroll the page with and v, and select	Off <b>¢</b>	<b>(~</b> ACH580	0.0 rpm
	Dup 99 Motor data and press Complete list		
	95 HW configuration		•
	96 Syster	n	•
	97 Motor	control	•
	98 User r	notor parameters	•
	99 Motor	data	▶ ()
	Back	22:52	Select
Scroll the page with (-) and (), and select	Off�	ACH580	0.0 rpm
parameter 99.13 ID run requested and press	Off <b>¢</b> 99 Motor	<b>C</b> ACH580	0.0 rpm
parameter <b>99.13 ID run requested</b> and press (Select) (or $$ ).	Off <b></b> 99 <b>Motor</b> 99.09 Moto	C ACH580	0.0 rpm 1430 rpm
parameter <b>99.13 ID run requested</b> and press (Select) (or ).	Off <b>۞</b> 99 <b>Motor</b> 99.09 Moto 99.10 Moto	C ACH580 data or nominal speed or nominal power	0.0 rpm 1430 rpm 0.75 kW
parameter <b>99.13 ID run requested</b> and press	Off <b>⊘</b> 99 <b>Motor</b> 99.09 Moto 99.10 Moto 99.11 Moto	C ACH580 data or nominal speed or nominal power or nominal cos φ	0.0 rpm 1430 rpm 0.75 kW 0.00
parameter <b>99.13 ID run requested</b> and press	Off <b>⊘</b> 99 <b>Motor</b> 99.09 Moto 99.10 Moto 99.11 Moto 99.12 Moto	C ACH580 data or nominal speed or nominal power or nominal cos φ or nominal torque	0.0 rpm 1430 rpm 0.75 kW 0.00 0.000 Nm
parameter 99.13 ID run requested and press (Select) (or ▶).	Off <b>⊘</b> 99 <b>Motor</b> 99.09 Moto 99.10 Moto 99.11 Moto 99.12 Moto <b>99.13 ID r</b>	← ACH580 or nominal speed or nominal power or nominal cos φ or nominal torque un requested	0.0 rpm 1430 rpm 0.75 kW 0.00 0.000 Nm None
parameter <b>99.13 ID run requested</b> and press	Off 99 Motor 99.09 Moto 99.10 Moto 99.11 Moto 99.12 Moto 99.13 ID ro Back	← ACH580 data — or nominal speed or nominal power or nominal cos ¢ or nominal torque un requested 22:52	0.0 rpm 1430 rpm 0.75 kW 0.00 0.000 Nm None Edit
Scroll the page with () and (), and select parameter 99.13 ID run requested and press (Select) (or ()). Select the ID run type and press (Save) (or	Off 99 <b>Motor</b> 99.09 Mot 99.10 Mot 99.11 Mot 99.12 Mot 99.13 ID r Back Off	C ACH580 data	0.0 rpm 1430 rpm 0.75 kW 0.00 0.000 Nm None Edit
Scroll the page with () and (), and select parameter 99.13 ID run requested and press (Select) (or ()). Select the ID run type and press (Save) (or ()).	Off 99 Motor 99.09 Moto 99.10 Moto 99.11 Moto 99.13 ID r Back Off 99.13 ID	C <sup>™</sup> ACH580 or nominal speed or nominal power or nominal cos φ or nominal torque un requested 22:52 C <sup>™</sup> ACH580 run requested	0.0 rpm 1430 rpm 0.75 kW 0.00 0.000 Nm None Edit 0.0 rpm
Scroll the page with () and (), and select parameter 99.13 ID run requested and press (Select) (or ()). Select the ID run type and press (Save) (or ).	Off 99 Motor 99.09 Moto 99.10 Moto 99.11 Moto 99.12 Moto 99.13 ID r Back Off 99.13 ID [0] Nor	C ACH580 data or nominal speed or nominal power or nominal cos φ or nominal torque un requested 22:52 C ACH580 run requested ne	0.0 rpm 1430 rpm 0.75 kW 0.00 0.000 Nm None Edit 0.0 rpm
Scroll the page with () and (), and select parameter 99.13 ID run requested and press (Select) (or ()). Select the ID run type and press (Save) (or ()).	Off ◆ 99 Motor 99.09 Moto 99.10 Moto 99.11 Moto 99.12 Moto <b>99.13 ID r</b> 0ff ◆ 99.13 ID [0] Nor [1] Nor	C ACH580 data or nominal speed or nominal power or nominal cos φ or nominal torque un requested 22:52 C ACH580 run requested non requested <	0.0 rpm 1430 rpm 0.75 kW 0.00 0.000 Nm None Edit 0.0 rpm
Scroll the page with () and (), and select parameter 99.13 ID run requested and press (Select) (or ()). Select the ID run type and press (Save) (or ()).	Off ◆ 99 Motor 99.09 Moto 99.10 Moto 99.11 Moto 99.12 Moto 99.13 ID r Back Off ◆ 99.13 ID [0] Nor [1] Nor [2] Red	C ACH580 data or nominal speed or nominal power or nominal cos φ or nominal torque un requested 22:52 C ACH580 run requested ne mal luced	0.0 rpm 1430 rpm 0.75 kW 0.00 Nm 0.000 Nm Edit 0.0 rpm
Scroll the page with () and (), and select parameter 99.13 ID run requested and press (Select) (or ()). Select the ID run type and press (Save) (or ()).	Off 99 Motor 99.09 Moto 99.10 Moto 99.11 Moto 99.12 Moto 99.13 ID r Back Off 99.13 ID [0] Nor [1] Nor [2] Red [3] Stai	C <sup>™</sup> ACH580 data or nominal speed or nominal power or nominal cos φ or nominal torque un requested 22:52 C <sup>™</sup> ACH580 run requested ne mal luced and still	0.0 rpm 1430 rpm 0.75 kW 0.00 0.000 Nm None Edit 0.0 rpm
Scroll the page with () and (), and select parameter 99.13 ID run requested and press (Select) (or ()). Select the ID run type and press (Save) (or ()).	Off 99 Motor 99.09 Moto 99.10 Moto 99.11 Moto 99.13 ID r Back Off 99.13 ID [0] Nor [1] Nor [2] Red [3] Stai [6] Adv	C <sup>™</sup> ACH580 data or nominal speed or nominal power or nominal cos φ or nominal torque <u>un requested</u> 22:52 C <sup>™</sup> ACH580 run requested ne mal luced and still and	0.0 rpm 1430 rpm 0.75 kW 0.00 0.000 Nm None Edit 0.0 rpm

<ul> <li>Panel LED starts blinking green to indicate an active warning (<i>AFF6</i>).</li> <li>The <i>AFF6</i> warning view is shown when no key has been pressed for one minute. Pressing (How to fix) shows text informing that the ID run will be done at the next start. You can hide the</li> </ul>	Off∳ ▲ Identi Motor	C ACH580 Warning AFF6 Aux code: 0000 0000 fication run identification run abo	0.0 rpm ) 22:52:29 out to be
<ul> <li>Will be dolle at the next start. You can hide the warning view by pressing → (Hide).</li> <li>Press the Hand key ( ) to start the ID run.</li> <li>In general, it is recommended not to press any control panel keys during the ID run. However, you can stop the ID run at any time by pressing the Off key ( ).</li> <li>During the ID run the arrow is rotating at the top.</li> <li>After the ID run is completed, text <b>ID run done</b> is shown. The LED stops blinking.</li> <li>If the ID run fails, fault <i>FF61 ID run</i> is shown. See chapter <i>Fault tracing</i> on page <i>183</i> for more information.</li> </ul>	Perforn Hide Hand⊘ 99 Mot 99.09 M 99.10 M 99.11 M 99.12 M 99.13 Tt Back	ned 22:52 ACH580 tor data Notor nominal speed Notor nominal power Notor nominal cos of Notor nominal torque Drun requested 22:52	How to fix \$0.0 rpm 1430 rpm 0.75 kW 0.00 0.000 Nm Normal Edit

## 3

### **Control panel**

#### Contents of this chapter

This chapter contains instructions for removing and reinstalling the assistant control panel and briefly describes its display, keys and key shortcuts. For more information, see *ACX-AP-x* assistant control panels user's manual (3AUA0000085685 [English]).

#### Removing and reinstalling the control panel

To remove the control panel, press the retaining clip at the top (1a) and pull it forward from the top edge (1b).

